

THE APPROXIMATION OF CONTINUOUS FUNCTIONS BY MULTILAYER PERCEPTRONS

IAN GLOVER

1. PRELIMINARIES

Definition 1.1. A *perceptron* is a unit consisting of a finite number of inputs and a single output. The output is a function of the inputs.

A *linear perceptron* is a perceptron which given inputs x_i , $i \in \{1, \dots, n\}$ has output \mathcal{O} given by

$$\mathcal{O} = \sum_{i \in I} w_i x_i + \theta$$

where $\theta \in \mathbb{R}$ is the *bias* and the $w_i \in \mathbb{R}$ are the weights. ie, the output is a linear combination of the inputs.

A *sigmoid perceptron* is a perceptron which given inputs x_i , $i \in \{1, \dots, n\}$ has output \mathcal{O} given by

$$\mathcal{O} = \frac{1}{1 + \exp(-\sum_{i \in I} w_i x_i + \theta)}$$

where $\theta \in \mathbb{R}$ is the *bias* and the $w_i \in \mathbb{R}$ are the weights.

Definition 1.2. For a continuous function $f : [a, b] \rightarrow \mathbb{R}$ we define the metric $\|f\|_{[a,b]}$ by

$$\|f\|_{[a,b]} = \int_{[a,b]} |f(x)| dx$$

The result we aim to prove is that given a bounded continuous function from a bounded subset of the real line we can approximate it to arbitrary accuracy using a multilayer perceptron network with one hidden layer. This will follow immediately from

Theorem. *Given a continuous function $f : [a, b] \rightarrow \mathbb{R}$ and $\varepsilon > 0$ n 1-input perceptrons with output functions $\mathcal{O}_{1i} : \mathbb{R} \rightarrow \mathbb{R}$, $i \in \{1, \dots, n\}$ and one n -input perceptron with output function $\mathcal{O}_{21} : \mathbb{R}^n \rightarrow \mathbb{R}$ and such that*

$$\|f - \mathcal{O}_{21}(\mathcal{O}_{11}, \dots, \mathcal{O}_{1n})\|_{[a,b]} < \varepsilon$$

To do this we will show firstly that any continuous function from a closed bounded subset of the real line can be approximated by a linear combination of indicator functions. Secondly we show that when restricted to a finite subset of the real line we can approximate an indicator function by a pair of sigmoid perceptrons. Putting these together will allow us to prove the above result.

2. THE APPROXIMATION OF THE CONTINUOUS FUNCTIONS

In this section we aim to show that any continuous function from a bounded subset of the real line can be approximated by a linear combination of indicator functions, with respect to the $\|\cdot\|_{[a,b]}$ metric given above.

Lemma 2.1. *If $f : [a, b] \rightarrow \mathbb{R}$ is a continuous function then f is uniformly continuous.*

Lemma 2.2. *If $f : [a, b] \rightarrow \mathbb{R}$ is a continuous function then the image f is closed and bounded.*

These results are standard results from any first course in analysis and will not be proved here.

Proposition 2.3. *Any continuous function $f : [0, 1] \rightarrow \mathbb{R}$ can be approximated by a finite combination of indicator functions.*

Proof. By lemma 2.1 f is uniformly continuous. Therefore given $\varepsilon > 0$ we can find $\delta(\varepsilon)$ such that $|f(x) - f(y)| < \varepsilon$ for all x, y such that $|x - y| < \delta(\varepsilon)$. Choose $N \in \mathbb{N}$ such that $N > \frac{1}{\delta}$, and let $S_k = [\frac{k}{N}, \frac{k+1}{N}]$ for $k \in \{0, \dots, N-1\}$. Define $g_{f,\varepsilon}$ by

$$g_{f,\varepsilon} = \sum_{k=0}^{N-1} f\left(\frac{2k+1}{2N}\right) \mathcal{I}_{S_k}(x)$$

Now if $x \in \mathcal{I}_{S_k}(x)$ then $|x - \frac{2k+1}{2N}| < \delta(\varepsilon)$ and so

$$\left|f(x) - f\left(\frac{2k+1}{2N}\right)\right| < \varepsilon$$

Thus

$$\begin{aligned} \|f - g_{f,\varepsilon}\|_{[0,1]} &= \int_{[0,1]} |f(x) - g_{f,\varepsilon}(x)| dx \\ &= \sum_{k=0}^{N-1} \int_{S_k} \left|f(x) - f\left(\frac{2k+1}{2N}\right)\right| dx \\ &< \sum_{k=0}^{N-1} \int_{S_k} \varepsilon dx \\ &= \sum_{k=0}^{N-1} \varepsilon \frac{1}{N} \\ &= \varepsilon \end{aligned}$$

□

Corollary 2.4. *Any continuous function $f : [a, b] \rightarrow \mathbb{R}$ can be approximated by a finite combination of indicator functions.*

Proof. Apply proposition 2.3 to $f\left(\frac{x-a}{b-a}\right)$. □

3. APPROXIMATION OF INDICATOR FUNCTIONS BY PERCEPTRONS

The next step is to show that we can approximate a step function using the linear combination of a pair of sigmoid perceptrons.

Recall from definition 1.1 that a sigmoid perceptron with one input x has output function:

$$\mathcal{O}_{(\alpha,\beta)}(x) = \frac{1}{1 + e^{-\alpha(x+\beta)}}$$

Now consider the heaviside function $H(x)$ given by

$$H(x) = \begin{cases} 0 & \text{if } x < 0 \\ 1 & \text{if } x \geq 0 \end{cases}$$

Lemma 3.1. *Given $\varepsilon > 0$ we can find $\alpha(\varepsilon)$ such that*

$$\|H - \mathcal{O}_{(\alpha,0)}\|_{[a,b]} < \varepsilon$$

Proof. Consider the condition $\mathcal{O}_{(\alpha,0)}(x) < \varepsilon$ for all $x < -k$ for some $k > 0$ to satisfy this we get:

$$\begin{aligned} \varepsilon &> \mathcal{O}_{(\alpha,0)}(x) \text{ for all } x < -k, \text{ some } k \in \mathbb{R}^+ \\ \frac{1+\varepsilon}{\varepsilon} &< e^{-\alpha x} \text{ for all } x < -k, \text{ some } k \in \mathbb{R}^+ \\ &< e^{-\alpha k} \\ \text{So } \alpha k &\leq \ln \varepsilon - \ln(1 + \varepsilon) \end{aligned}$$

This can be achieved by setting

$$\alpha = \frac{1}{k}[\ln \varepsilon - \ln(1 + \varepsilon)]$$

It is clear that if we do this then, by symmetry:

$$\mathcal{O}_{(\alpha,0)}(x) > 1 - \varepsilon \text{ for all } x > k$$

If we restrict H to $[a, b]$ where there is $k > 0$ such that $[-k, k] \subset [a, b]$ we now get

$$\begin{aligned}
\|H - \mathcal{O}_{(\alpha,0)}\|_{[a,b]} &= \int_a^b |H(x) - \mathcal{O}_{\alpha,0}| dx \\
&= \int_a^{-k} |0 - \mathcal{O}_{\alpha,0}| dx \\
&\quad + \int_{-k}^k |H(x) - \mathcal{O}_{\alpha,0}| dx \\
&\quad + \int_k^b |1 - \mathcal{O}_{\alpha,0}| dx \\
&= \int_a^{-k} \varepsilon dx \\
&\quad + \int_{-k}^k |H(x) - \mathcal{O}_{\alpha,0}| dx \\
&\quad + \int_k^b \varepsilon dx \\
&< (-k - a)\varepsilon + \int_{-k}^k dx + (b - k)\varepsilon \\
&= (b - a - 2k)\varepsilon + 2k
\end{aligned}$$

If we set $k = \varepsilon$ we get $\|H - \mathcal{O}_{(\alpha,0)}\|_{[a,b]} < (b - a)\varepsilon$. \square

Now consider $[c, d] \subset [a, b]$ then $\mathcal{I}_{[c,d]}(x) = H(x - a) - H(x - b)$ so we get the following immediate corollary to the above

Corollary 3.2. *If $[c, d] \subset [a, b]$ then given $\varepsilon > 0$ there exists α such that*

$$\|\mathcal{I}_{[c,d]} - (\mathcal{O}_{(\alpha,-a)} - \mathcal{O}_{(\alpha,-b)})\|_{[a,b]} < \varepsilon$$

4. THE APPROXIMATION OF CONTINUOUS FUNCTIONS BY MLPs

We are now in a position to prove the theorem in stated section 1, namely

Theorem 4.1. *Given a continuous function $f : [a, b] \rightarrow \mathbb{R}$ and $\varepsilon > 0$ n 1-input perceptrons with output functions $\mathcal{O}_{1i} : \mathbb{R} \rightarrow \mathbb{R}$, $i \in \{1, \dots, n\}$ and one n -input perceptron with output function $\mathcal{O}_{21} : \mathbb{R}^n \rightarrow \mathbb{R}$ and such that*

$$\|f - \mathcal{O}_{21}(\mathcal{O}_{11}, \dots, \mathcal{O}_{1n})\|_{[a,b]} < \varepsilon$$

Proof. By proposition 2.3 there exists a function

$$g_{f,\varepsilon} = \sum_{k=0}^{N-1} f\left(\frac{2k+1}{2N}\right) \mathcal{I}_{[\frac{k}{N}, \frac{k+1}{N}]}(x)$$

such that $\|f - g_{f,\varepsilon}\|_{[a,b]} < \varepsilon$.

By corollary 3.2 we have can find α such that

$$\left\| \mathcal{I}_{[\frac{k}{N}, \frac{k+1}{N}]} - (\mathcal{O}_{(\alpha, -\frac{k}{N})} - \mathcal{O}_{(\alpha, -\frac{k+1}{N})}) \right\|_{[a,b]} < \frac{\varepsilon}{N} \text{ for all } k \in \{0, \dots, N-1\}.$$

Thus we define $P(x) : [a, b] \rightarrow \mathbb{R}$ by

$$P(x) = \sum_{k=0}^{N-1} f\left(\frac{2k+1}{2N}\right) \left(\mathcal{O}_{(\alpha, -\frac{k}{N})}(x) - \mathcal{O}_{(\alpha, -\frac{k+1}{N})}(x) \right)$$

Then

$$\begin{aligned} \|f - P\|_{[a,b]} &\leq \|f - g_{f,\varepsilon}\|_{[a,b]} + \|g_{f,\varepsilon} - P\|_{[a,b]} \\ &< \varepsilon + \sum_{k=0}^{N-1} f\left(\frac{2k+1}{2N}\right) \left\| \mathcal{I}_{[\frac{k}{N}, \frac{k+1}{N}]} - \left(\mathcal{O}_{(\alpha, -\frac{k}{N})}(x) - \mathcal{O}_{(\alpha, -\frac{k+1}{N})}(x) \right) \right\|_{[a,b]} \\ &< \varepsilon + \frac{\varepsilon}{N} \sum_{k=0}^{N-1} f\left(\frac{2k+1}{2N}\right) \\ &< \varepsilon \left(1 + \frac{N}{N} \sup_{x \in [a,b]} f(x) \right) \\ &< \varepsilon \left(1 + \sup_{x \in [a,b]} f(x) \right) \end{aligned}$$

By lemma 2.2 $|\sup_{x \in [a,b]} f(x)| < K$ for some $K \in \mathbb{R}$.

Thus to construct the network to approximate f we have a hidden layer with $2N$ single input perceptrons with weight α and biases $-\frac{k}{N\alpha}$ for $k \in \{1, \dots, N\}$ (two for each k). We then have single output perceptron with no bias and weights as given by the definition of $P(x)$. \square

From this we get the following

Corollary 4.2. *Any piecewise continuous function from a closed bounded subset of the real line can be approximated to arbitrary accuracy by a multilayer perceptron network with one hidden layer.*

Corollary 4.3. *Any piecewise continuous function from a closed bounded subspace of \mathbb{R}^n to \mathbb{R}^m can be approximated to arbitrary accuracy by a multilayer perceptron network with one hidden layer.*

Corollary 4.4 (Reasonably but not 100% sure of this). *Any Riemann integrable function from \mathbb{R}^n to \mathbb{R}^m can be approximated to arbitrary accuracy by a multilayer perceptron network with one hidden layer.*

E-mail address: `inglover@iname.com`